

AMENDMENTS TO THE CLAIMS:

This listing of claims will replace all prior versions, and listings, of claims in the application:

Listing of Claims:

1. (Currently amended) A numeric-control machine comprising a flatbed provided with: a horizontal working surface, on which a workpiece is to be positioned;[[,]] a machining head, which is mobile in space above the working surface;[[,]] and a supporting structure, which is designed to support and displace said machining head in space above the working surface;[[,]] ~~said machine being characterized in that~~ said supporting structure comprising[es:] a floating platform mounted mobile above the working surface;[[,]] and a plurality of articulated supporting arms designed to support the floating platform above the aforesaid working surface on opposite sides of the platform;[[,]] each articulated arm being mobile in a vertical plane and being designed to connect the flatbed of the machine with the overlying floating platform, each articulated arm comprising two half-arms hinged via a first connection hinge to enable the two half-arms to rotate about a first axis of rotation perpendicular to said vertical plane.

2. (Currently amended) The machine according to Claim 1, characterized in that said two half-arms of each articulated supporting arm ~~each of said articulated supporting arms comprises two half-arms that are hinged to one another via a first connection hinge that enables the two half-arms to rotate about a first pre-set axis of rotation, and are separately hinged one to the flatbed of the machine with a second connection hinge and the other to the body of the floating platform with a third connection hinge so as to be able to in such a way as to be able to~~ rotate freely about a respective second axis of rotation and a respective third axis of rotation parallel to said first axis of rotation.

3. (Previously amended) The machine according to Claim 2, characterized in that said plurality of articulated arms comprises at least one pair of articulated supporting arms that are arranged aligned and co-planar to one another in a substantially specular configuration with respect to one another, in such a way that said first connection hinge, said second connection hinge and said

third connection hinge belonging to said two articulated supporting arms are positioned in space at the vertices of a hexagon.

4. (Previously amended) The machine according to Claim 3, characterized in that the articulated supporting arms that form each pair of articulated arms extend on one and the same plane of movement substantially perpendicular to the longitudinal axis of said working surface of the machine.

5. (Previously amended) The machine according to Claim 1, characterized in that it comprises means for movement which are able to move upon command the two half-arms of each articulated arm about said first axis of rotation, said second axis of rotation and said third axis of rotation independently of one another.

6. (Previously amended) The machine according to Claim 5, characterized in that said means for movement comprise at least one driving unit set in a position corresponding to said first connection hinge, said second connection hinge and/or said third connection hinge of the articulated arm.

7. (Previously amended) The machine according to Claim 1, characterized in that said floating platform is provided with a longitudinal through opening that extends in a direction parallel to the longitudinal axis of said working surface; the machining head being designed to slidably engage said longitudinal through opening.